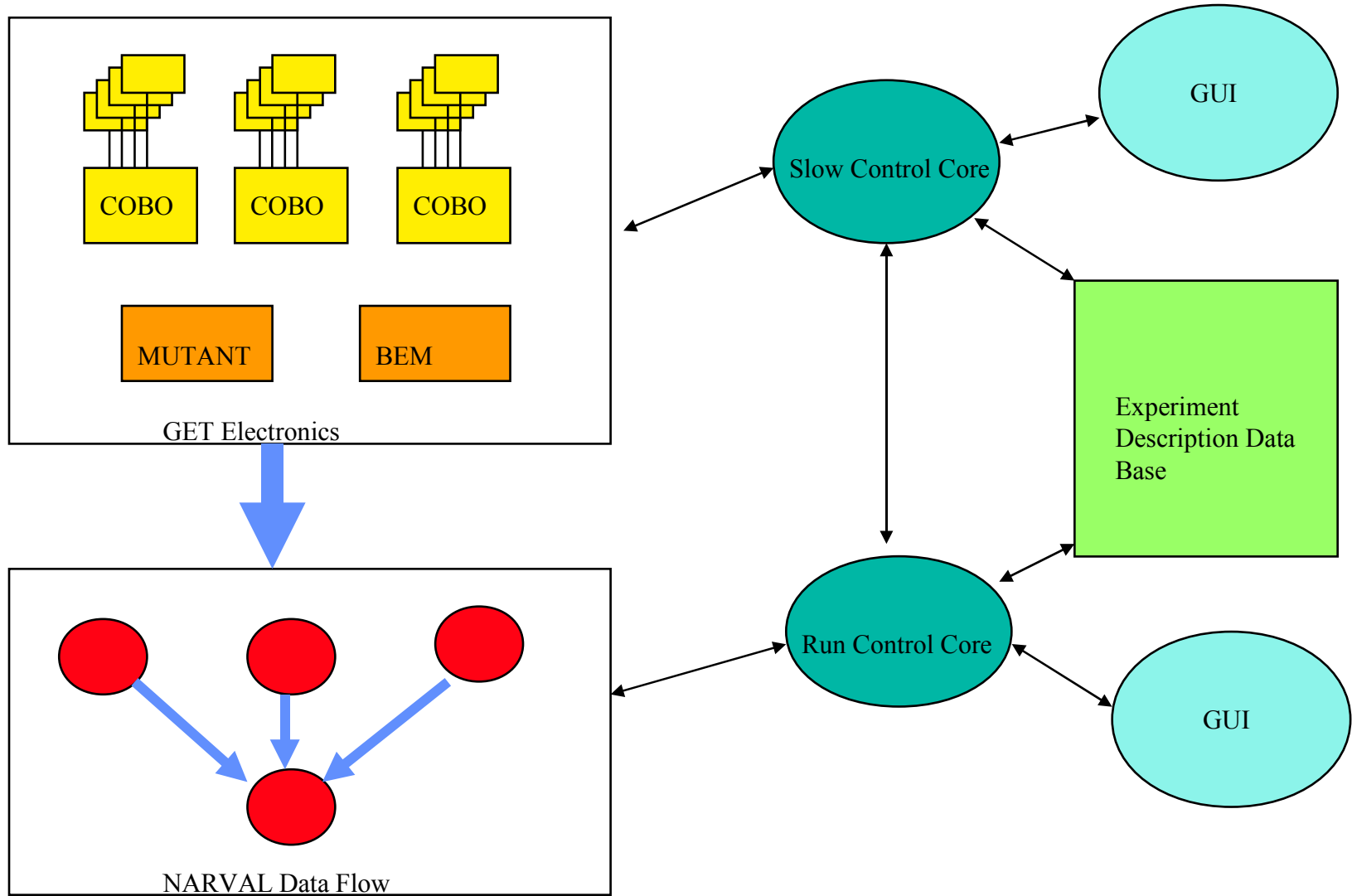


GANIL Run Control System

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GANIL Run Control system

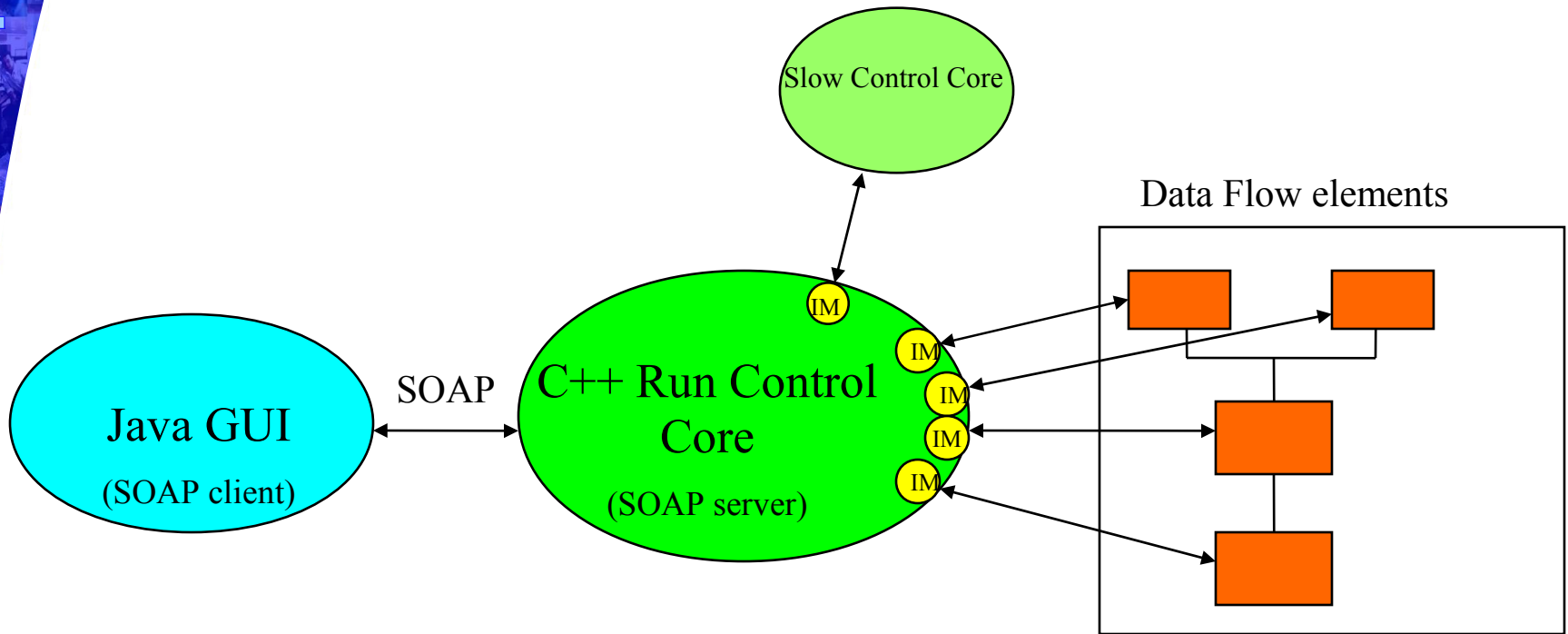


General overview of Slow and Run Control for GET

Run Control main tasks :

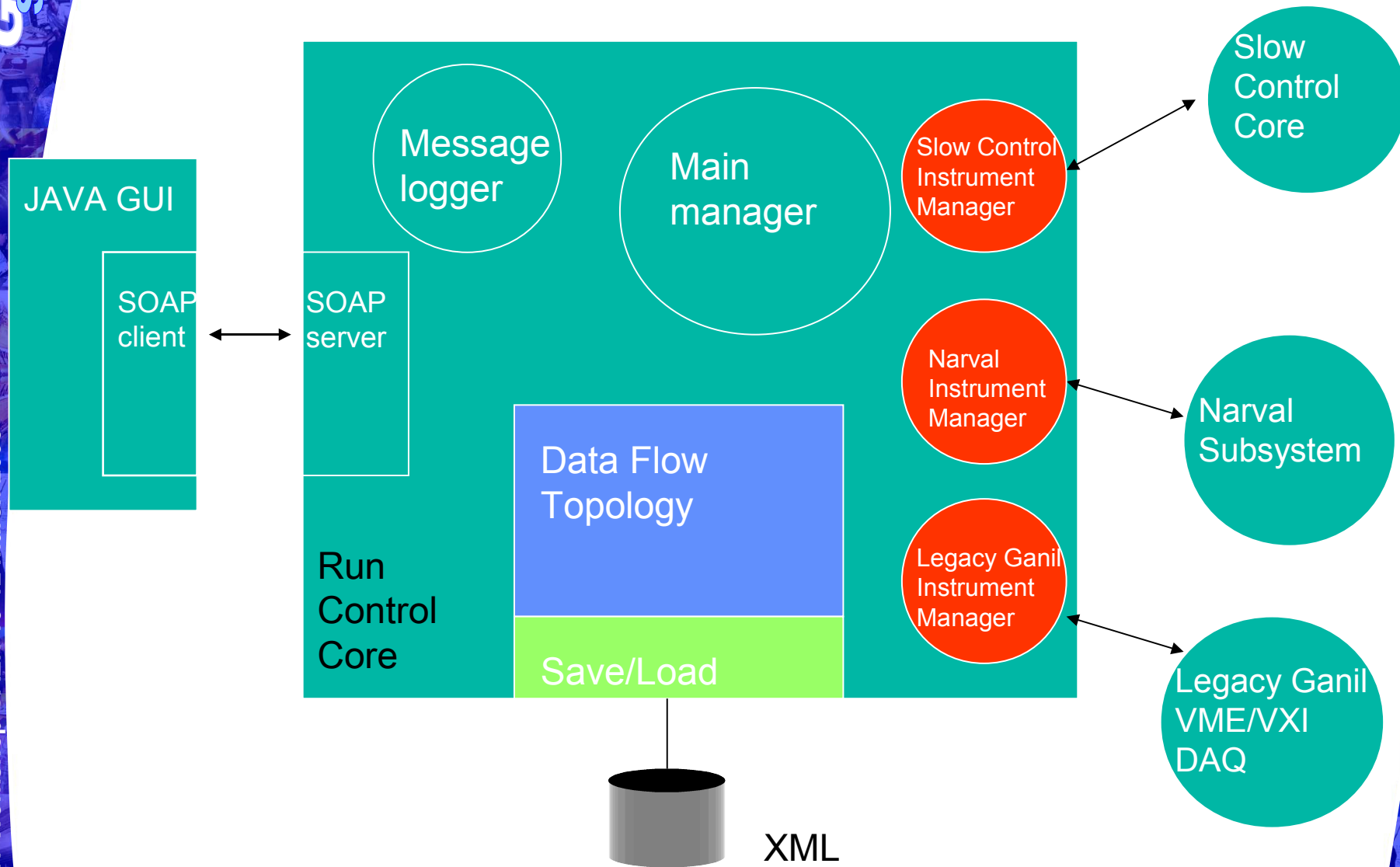
- ◆ **Configure DAQ for a run by selecting data flow elements**
- ◆ **Save/restore a configuration**
- ◆ **Commands to control data flow elements**
- ◆ **Commands to globally setup, start, stop electronics through Slow Control Core**
- ◆ **Monitor DAQ (status, data rates...)**
- ◆ **Handle error/info messages**
- ◆ **Log book**
- ◆ **User-friendly graphical interface, separated from the core of the application**

GANIL Run Control System



- Run Control Core accesses data flow components with specific communication protocols encapsulated in « Instrument Managers »
- Run Control Core written in C++ with gSOAP library
- WSDL file generated by gSOAP
- Java GUI integrates SOAP client stub thanks to WSDL file

GANIL Run Control System



Data Flow Topology Description

What are the objects involved in a topology ?

➤ Instruments :

- Narval subsystem (contains actors)
- Narval actors (producers, mergers, filters, storage actor ...)
- Legacy Ganil VME/VXI DAQ (Vamos, Lise, Must2 ...)
- MIDAS DAQ from Daresbury (Exogam, Tiara ...)

➤ Oriented links :

represent data flow from one instrument to another



Data Flow Topology Description

What are the objects involved in a topology ? (cont'd)

➤ Instrument Parameters :

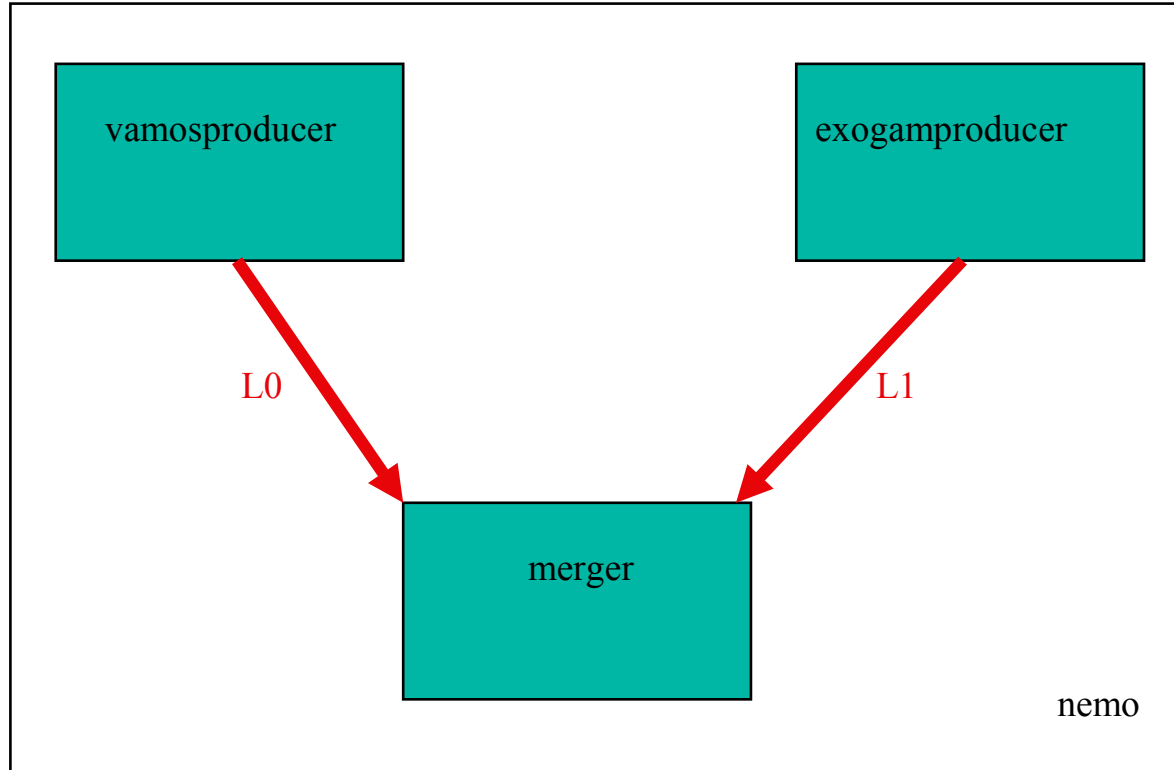
Parameters belonging to an instrument. They have a name, a type (string, integer, boolean ...), a value and some access rights (read-only, read-write ...).

Example :

for the storage actor, name of the file where to store incoming data

Data Flow Topology Description

Example of a topology:



Data Flow Topology Description

How to save the data flow topology description ?

→ XML file

```
<?xml version="1.0" encoding="UTF-8" standalone="no" ?>
- <configuration xmlns="etest.xml">
- <narval hostname="ganp754" name="nemo">
- <actor executable_file="acqsbuf" hostname="ganp754" log_level="debug" name="vamosproducer">
  <parameter dynamic="true" name="acqvmecrate" permission="read_only" type="string_type" value="ganlo1" />
</actor>
<actor executable_file="acqsbuf" hostname="ganp754" log_level="debug" name="exogamproducer" />
<actor executable_file="evtnum_eventbuilder" hostname="ganp754" log_level="debug" name="merger" />
</narval>
<link buffer_size="1000000" destination="merger" destination_port="fifo" name="L0" source="vamosproducer"
source_port="fifo" />
<link buffer_size="1000000" destination="merger" destination_port="fifo" name="L1" source="exogamproducer"
source_port="fifo" />
</configuration>
```

XML generation and parsing are based on Xerces library

(DOM for file generation, SAX for file parsing)

Data Flow Topology Description

How to build the data flow topology ?

→ a complete set of web services to create and modify instruments, links and parameters.

- `CreateNarval` adds a Narval subsystem
- `CreateActor` adds a Narval actor
- `CreateStorage` adds a Narval storage actor
- `CreateEventBuilder` adds a Narval event builder
- `CreateVmecom` adds a legacy Ganil VME crate
- `CreateLink` defines a link between two instruments
- `CreateParameter` adds a parameter to an instrument
- `SetParameterValue` modifies parameter value
- ...

Data Flow Topology Description

How to get information about an existing topology ?

- [GetEquipmentCount](#) number of instruments
- [GetLinkCount](#) number of links
- [GetParameterCount](#) number of parameters for a given instrument
- [GetEquipmentByIndex](#) returns info on equipment of a given index
- [GetLinkByIndex](#) returns info on link of a given index
- [GetParameterByIndex](#) returns info on parameter of a given index in an instrument
- [GetParameterType](#) returns parameter type
- [GetParameterValue](#) returns parameter value
- ...

The configuration graphical user interface uses these web services to allow the user to fully manipulate the topology of the system.

Run Control Graphical User Interface

Current GUI only for building and modifying the topology :

- developed in Java
- uses web services to get the topology from Run Control Core, modify the topology or create a new one from scratch
- SOAP client side generated thanks to WSDL file provided by RCC
- error messages handled by Log4j
- allows the user to add an instrument of any known type in the topology
- allows the user to add a link between two existing instruments
- topology is always displayed in a graphical window and in a tree

Development of command and monitoring GUI not yet started

GANIL Run Control system

Configuration d'equipements du GANIL

Fichier

New Open Load Save Save as

Graphical Setup

VMCOM MIDAS NARVAL LINK

Offline

Explorer

Add an Equipment

Add a link

- Equipment configuration
 - VAMOS
 - MERGER (Lien1)
 - MIDAS0
 - MERGER (Lien2)
 - MERGER
 - VAMOS (Lien1)
 - MIDAS0 (Lien2)
 - STORAGE (Lien3)
 - STORAGE
 - MERGER (Lien3)

Graph generation

```
graph TD; VAMOS[VAMOS] --> MERGER[MERGER]; MIDAS0[MIDAS0] --> MERGER; MERGER --> STORAGE[STORAGE];
```

The diagram illustrates the system architecture. At the top, two boxes labeled 'VAMOS' and 'MIDAS0' are connected by arrows to a central box labeled 'MERGER'. The 'MERGER' box contains an icon of a person working with a brick wall. Below the 'MERGER' box, an arrow points to a box labeled 'STORAGE' containing an icon of a hard drive. The interface also includes a file explorer on the left, a toolbar with 'New', 'Open', 'Load', 'Save', and 'Save as' buttons, and a 'Graphical Setup' section with icons for 'VMCOM', 'MIDAS', 'NARVAL', and 'LINK'. A red 'Offline' button is located in the top right corner.

Error messages management

- Use of Log4j and Log4cxx
- Log4ada developed by Xavier Grave (Orsay) for Narval
 - works like Log4j/Log4cxx
- Legacy Ganil VME/VXI crates use a RPC-based protocol to send messages
 - Run Control Core will include an RPC server to translate into Log4cxx
- Message Logger centralizes all messages and log them on a disk file (XML)
- Messages can also be visualized in a graphical tool like Chainsaw, with advanced sorting capabilities

States monitoring and management

- each instrument manager contains a state machine reflecting the one of the real DAQ instrument (a monitoring thread asks for instrument state continuously)
- Run Control Top Manager contains a global state machine updated accordingly to the instrument state machines
- global state and individual states are checked when a command is issued by the user
- a command on the system might have an impact on the instrument state machines and the global state machine
- not yet implemented ...

NARVAL

- ◆ Originally developed by IPN Orsay
- ◆ Today, collaborative development with IPNO, CSNSM, GANIL, LPC Caen
- ◆ Distributed Acquisition System
- ◆ Developed in Ada95
 - ◆ Object Oriented programming
 - ◆ Strongly typed language
 - ◆ Robust applications
 - ◆ Distributed processes by using Annex E (CORBA equivalent)
- ◆ Easy to link with C++
- ◆ Used for AGATA DAQ
- ◆ *Web site : <http://narval.in2p3.fr/>*

NARVAL

■ Main components :

- ◆ A main process to handle the state of all the configuration (Coordinator)
- ◆ Set of actors to manage the data flow
 - ◆ Producer : input of data flow (hardware or other DAQ)
 - ◆ Intermediary : acts as a NxM soft switch that can filter data
 - ◆ Consumer : end of data flow (data storage, output to other DAQ,...)
- ◆ Logging of error/info messages (Log4Ada)

■ Data flow transport over Unix fifo, TCP/IP, Infiniband

■ Communication via Web Services (SOAP) with the « Coordinator »

NARVAL

Specific actors already developed for Ganil DAQ :

- interface for legacy Ganil VME/VXI crates (Ganil development)
- event builder based on event number (Ganil development)
- storage actor to write data flow on disk (LPC Caen development)