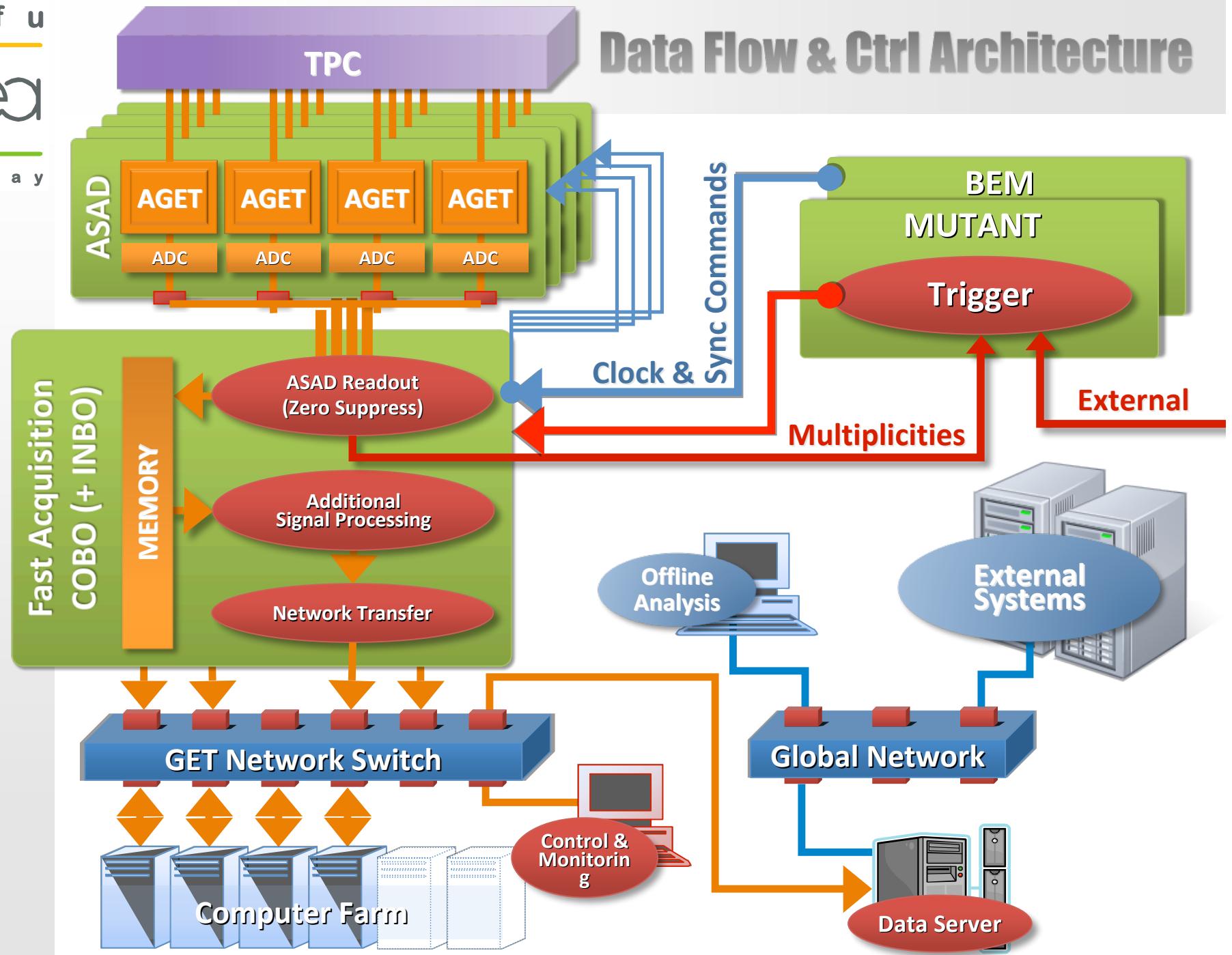


GET System Overview

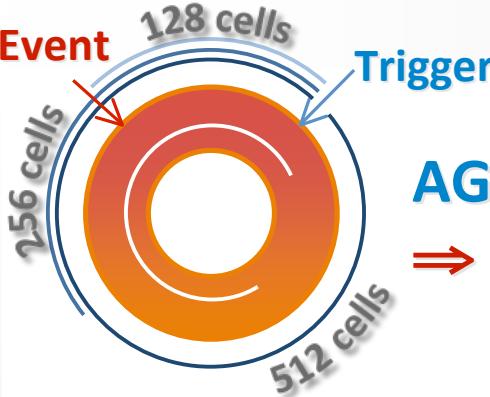
Shebli Anvar, CEA Irfu

GET Workshop, Caen, France
March 10-12, 2009

Data Flow & Ctrl Architecture



Synchronous Domain



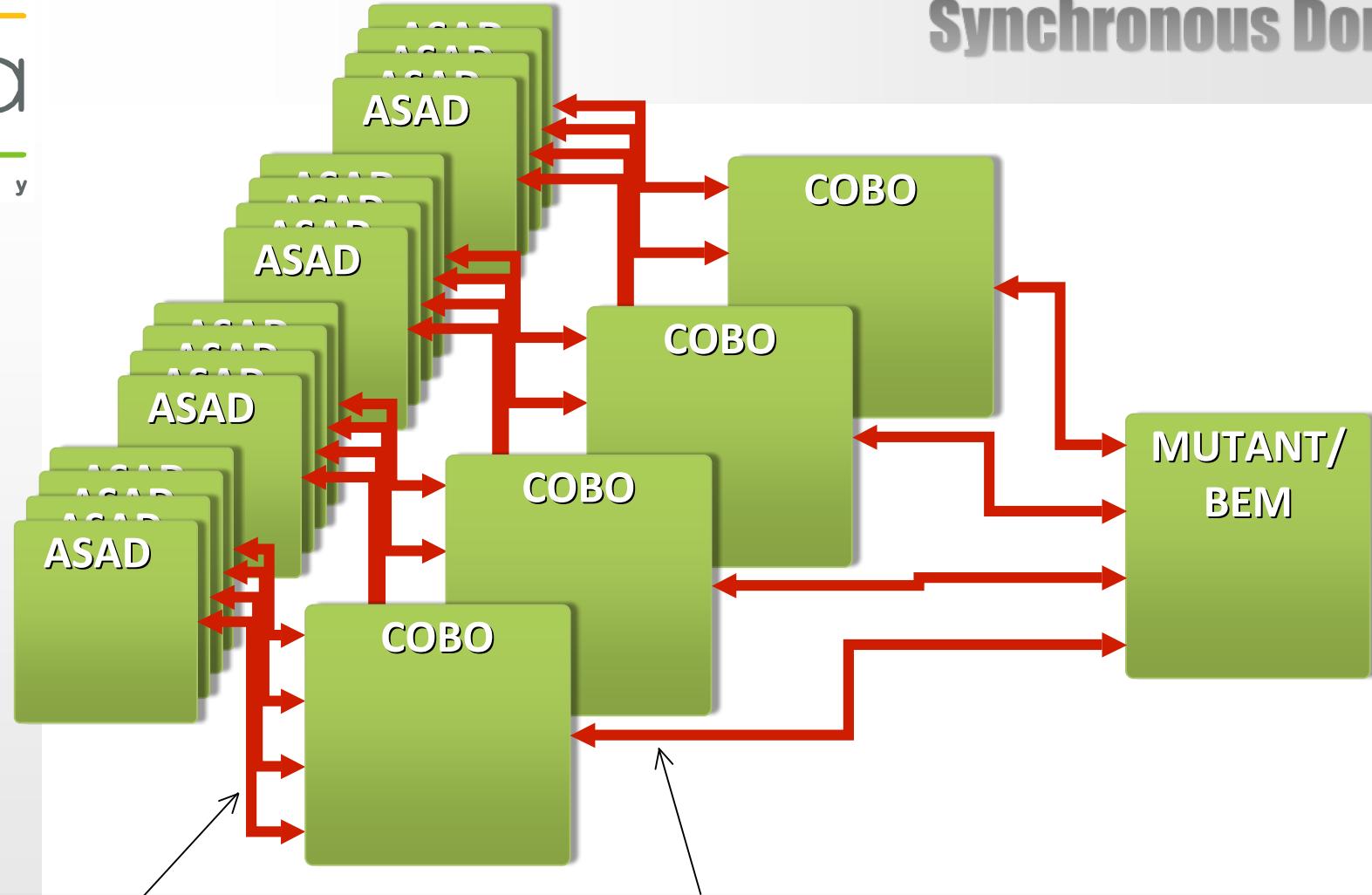
AGET Circular Memory: $10 \text{ ns} \times 512 = 5.12 \mu\text{s}$
 \Rightarrow L1 trigger roundtrip $\leq 5 \mu\text{s}$ (smallest case)

- The later the trigger, the more cells to read
- Trigger must be late enough to allow for drift
 \Rightarrow Trigger I/O timing: deterministic and configurable
- Clock distribution : 100 MHz, jitter $\sim 1\text{ns}$
- At least one full precision synchronous « start » necessary
- Timing calibration

\Rightarrow Same infrastructure for synchronous commands?
e.g. trigger I/O, readout, roundtrip timing calibration

+ integration of clock and trigger I/O cabling

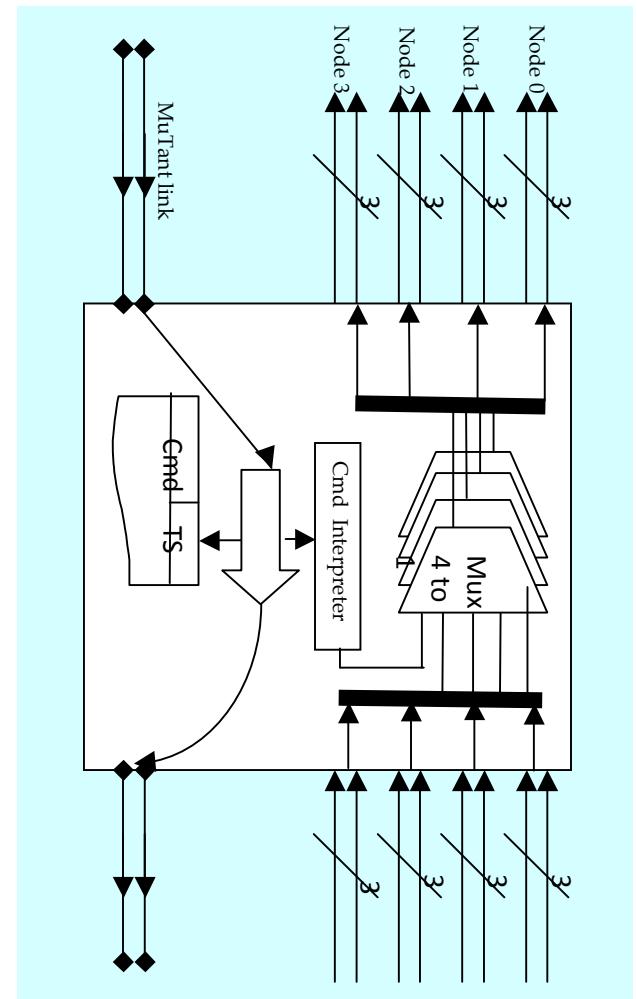
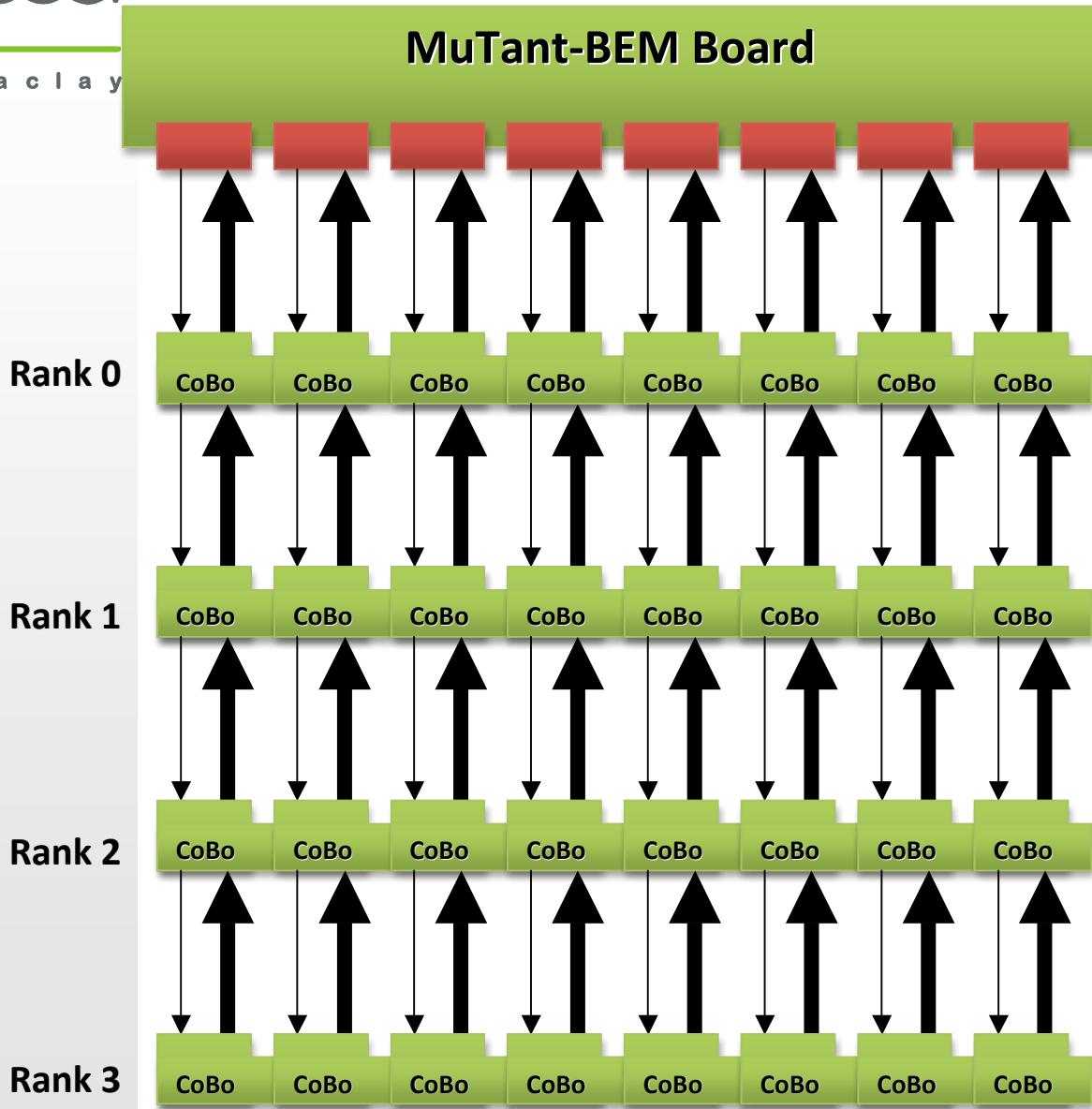
Synchronous Domain



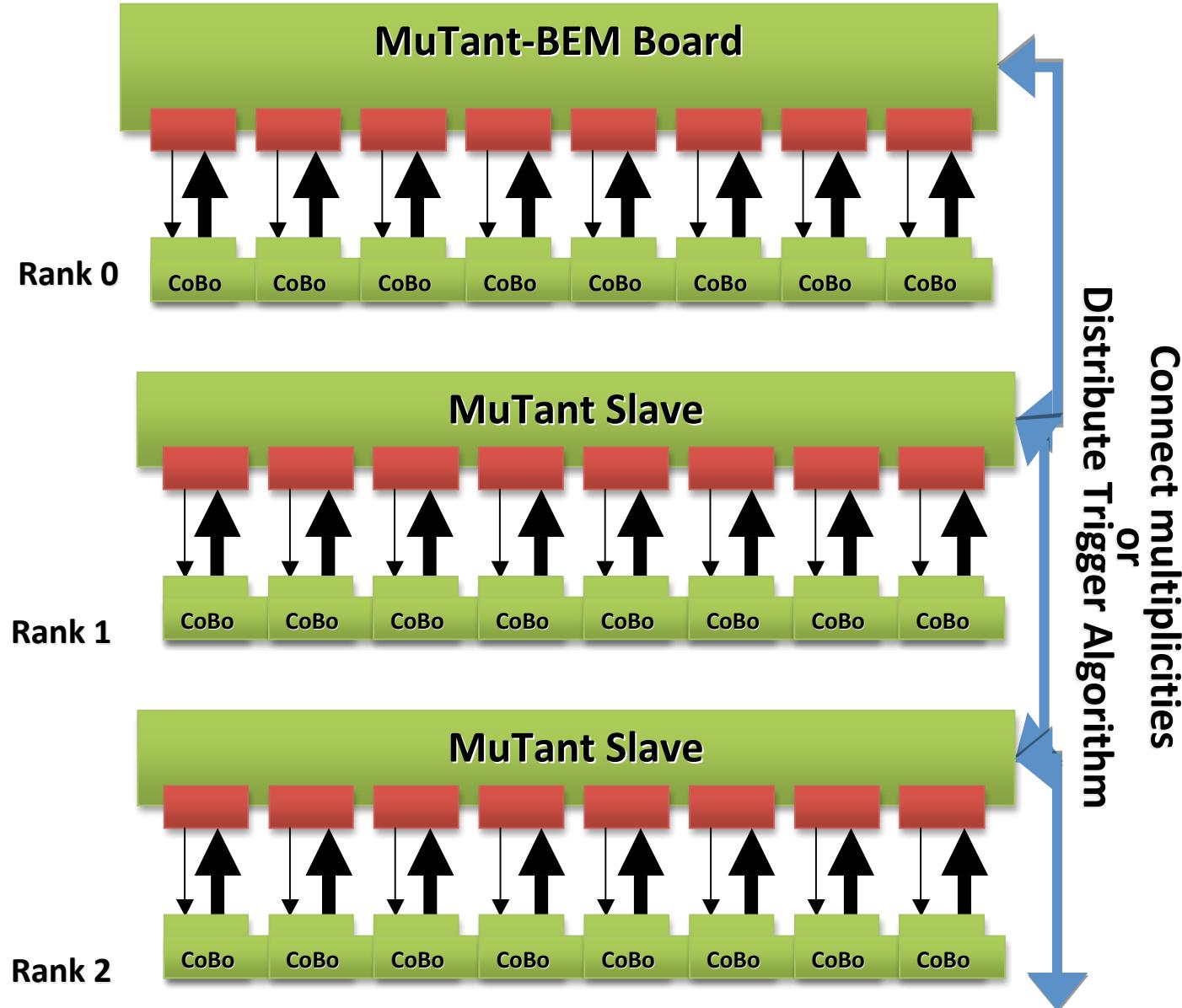
Same infrastructure for clock and trigger I/O

Max number of COBOS: 32 \leftrightarrow 36864 channels
Front panel & crate limits : daisy chaining MUTANTS or COBOS

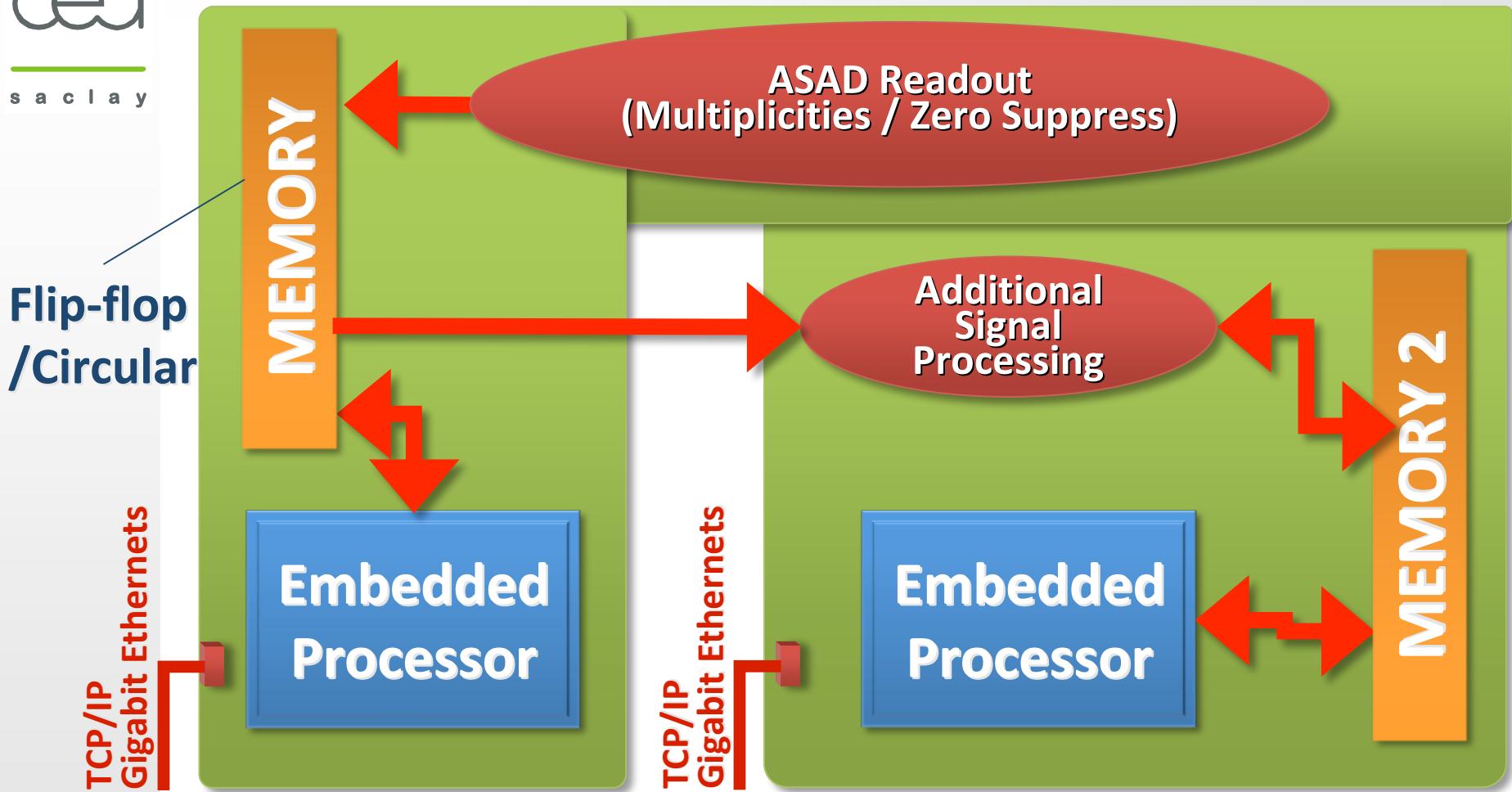
Synchronous Domain: Daisy-chaining CoBoS



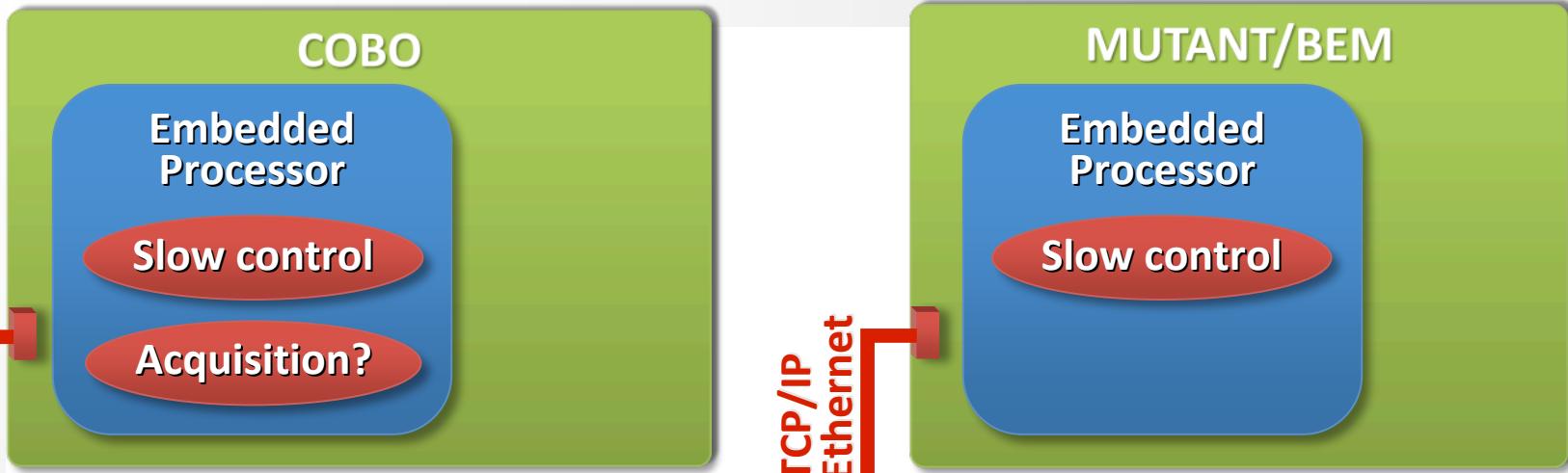
Synchronous Domain: Daisy-chaining MUTANTs



Some Design Alternatives



Memory bus is probably the limiting factor
Consider TCP/IP firmware co-processing, DSP?
→ Modular design for the COBO acquisition subsystem



- At least for slow control
- Possibly for data acquisition
(70 MByte/s under VxWorks over embedded processor)
- Choice of operating system
 - Linux
 - « free »
 - « same » as desktop
 - Real-time (VxWorks, RTEMS...)
 - driver development much easier
 - better control through strict prioritization
 - VxWork is not « free » (development licence and runtime)
 - RTEMS is « free »

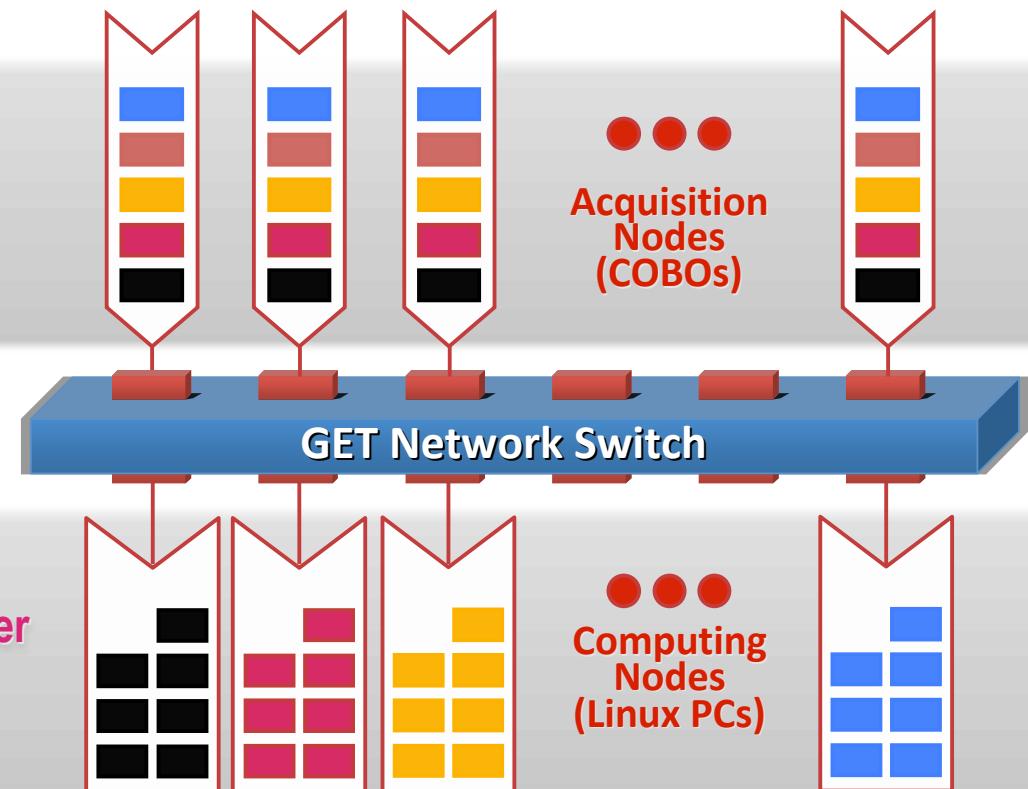
Routing Data over Network According to « Time Slice »

- **Intrinsic parallelism**

- Relates to detector spread
- Static configuration
- High reliability

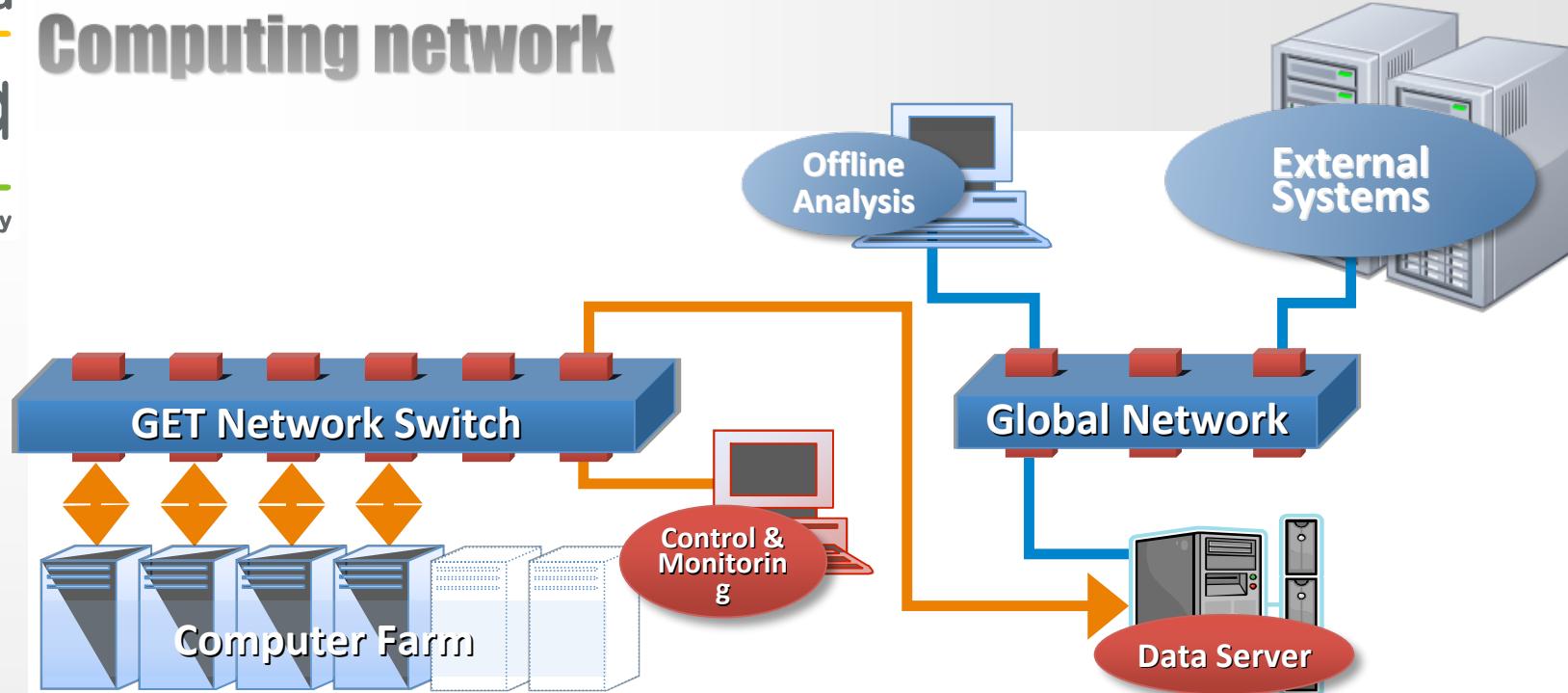
- **Performance parallelism**

- Relates to available computing power
- Dynamic configuration
- Scalability, lower reliability



Routing based on Time stamp / Event number given by
MUTANT
→ Some Adapted Data Frame Format (COBO firmware)

Computing network



- **Distributed application**
- **Adaptable to different detector contexts**
- **Adaptable to different facility contexts**

Use of middleware for distributed applications
Modular components
Deliver libraries (C++ and/or Java) for context integration